

Possible mission architectures for a GRACE follow-on mission including a study on upgraded instrumentation suites, and multiple satellite pairs in moderately-inclined orbits

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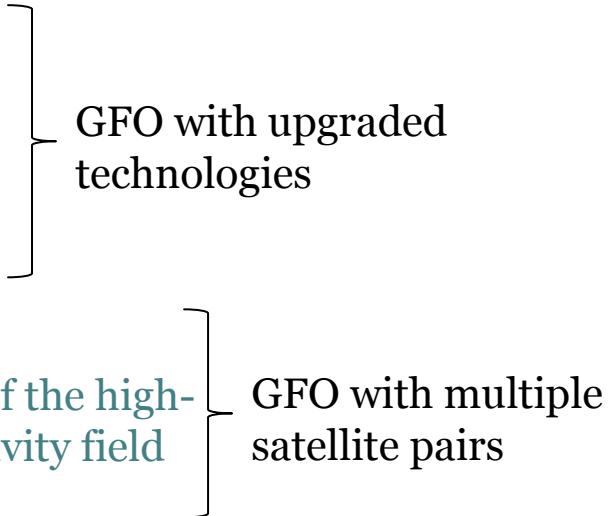
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Presentation outline

- Limitations of GRACE
- Simulation procedure
- GRACE Follow-On with upgraded technologies
- GRACE Follow-On with multiple satellite pairs
- Future work

Limitations of GRACE

- Instrument errors
 - Satellite-to-satellite ranging
 - Accelerometers
- Orbital altitude
- Temporal aliasing
 - Caused by under-sampling of the high-frequency changes in the gravity field
- Force model errors
 - Ocean and solid Earth tides
 - Atmospheric and non-tidal mass variations



GFO with upgraded technologies

GFO with multiple satellite pairs

Simulation procedure

- Goal: recover time-variable hydrological and ice mass variations in the presence of instrument and temporal aliasing errors
- Simulated error sources
 - Satellite-to-satellite range-rate errors
 - Removal of non-conservative forces
 - Satellite positioning errors
 - Imperfections in geophysical models (AOD & tides)

GFO with upgraded technologies

- Interferometric laser ranging system
 - Replaces the K-band microwave ranging system
 - Reduces error RMS from $\sim 0.2 \mu\text{s}$ to $\sim 0.6 \text{ nm/s}$
- Gravitational reference sensor (GRS)
 - Proof mass isolated within the body of the spacecraft
 - Micro-thrusting is used to maintain the position of satellite with respect to the proof mass resulting in a drag-free system
 - Reduces errors associated with on-board accelerometers
- Reduction in orbital altitude
 - Lower altitude satellites are more sensitive to higher spatial resolution features of gravity field
 - Would need to be accompanied by GRS to maintain orbital altitude

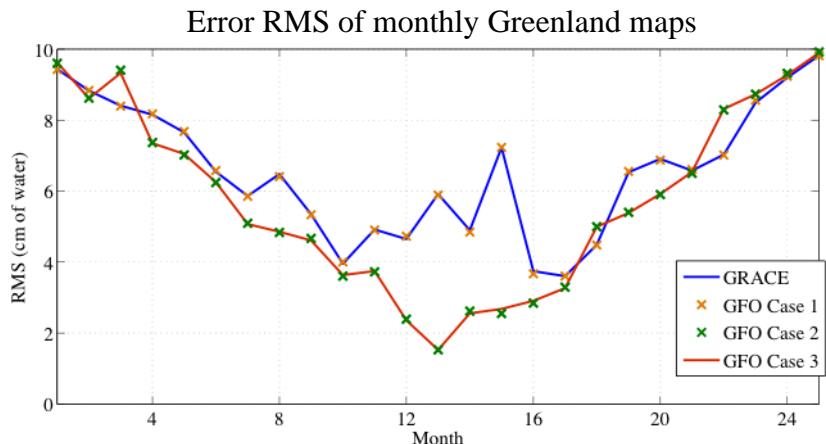
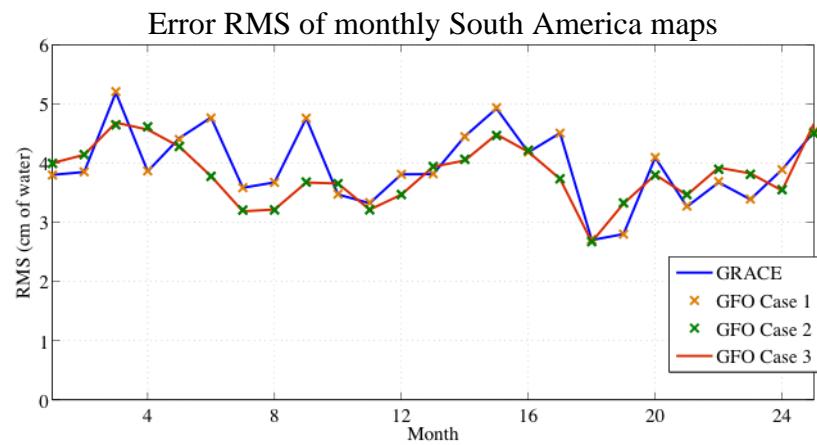
GFO with upgraded technologies

- Four different missions are simulated:
GRACE and three possible GFO configurations

Mission	Altitude / satellite separation	Range-rate noise	Removal of non-conservative forces
GRACE	480 km / 220 km	K-band	Accelerometer
GFO Case 1	480 km / 220 km	Laser	Accelerometer
GFO Case 2	250 km / 50 km	K-band	GRS (drag-free)
GFO Case 3	250 km / 50 km	Laser	GRS (drag-free)

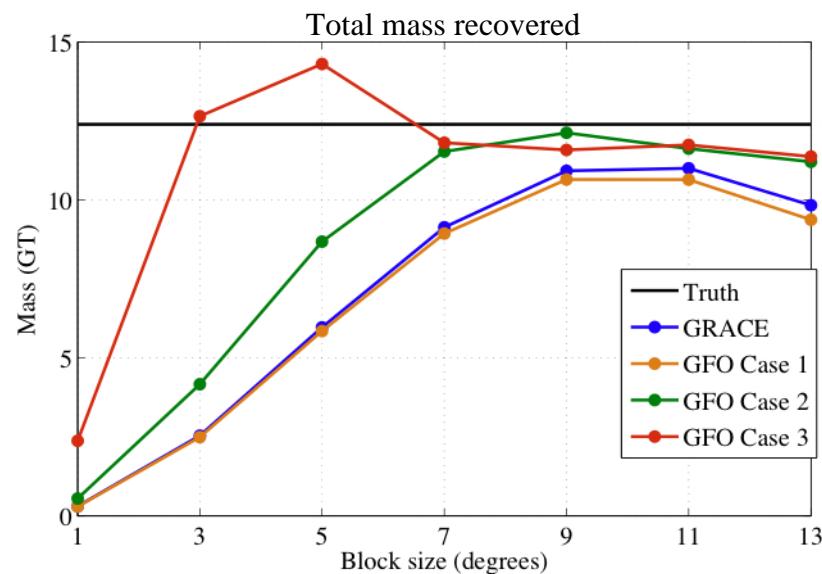
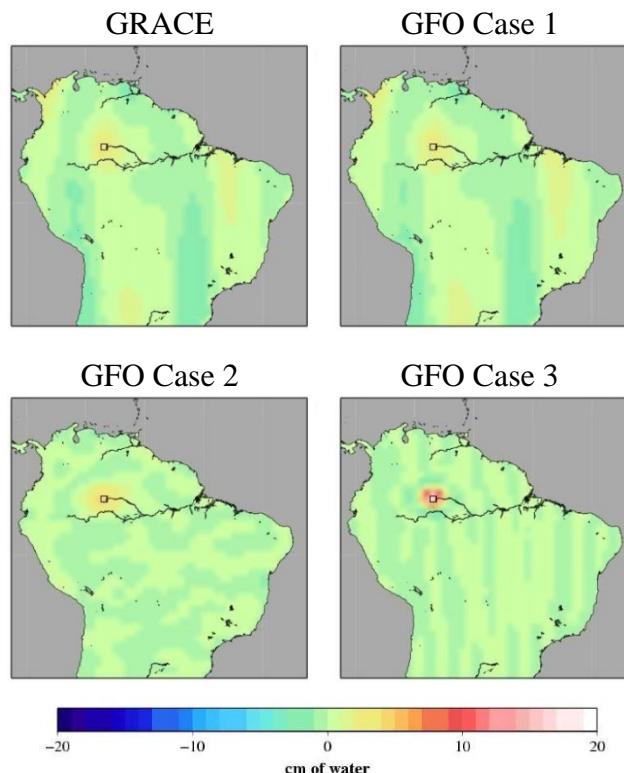
- GFO Case 3 is best-case scenario
- GFO Case 1 and Case 2 are “hybrid” missions
- Simulations estimate monthly regional mascon gravity estimates for South America and Greenland

GFO with upgraded technologies



GFO with upgraded technologies

- Spatial resolution study



GFO with multiple satellite pairs

- Reducing temporal aliasing errors
 - Improving atmosphere, ocean, and tide models
 - Co-estimating parameters (i.e. tidal coefficients)
 - Multiple satellite pairs

GFO with multiple satellite pairs

- Multiple satellite pair configurations

Lower inclined satellite pair

+

Polar satellite pair

Repeat Period (revs/sidereal days)	Altitude (km)	Indination (deg)
360/23	312	63
236/15	291	65
157/10	301	65

Repeat Period (revs/sidereal days)	Altitude (km)	Indination (deg)
79/5	312	90

Compare these to a single pair of polar satellites

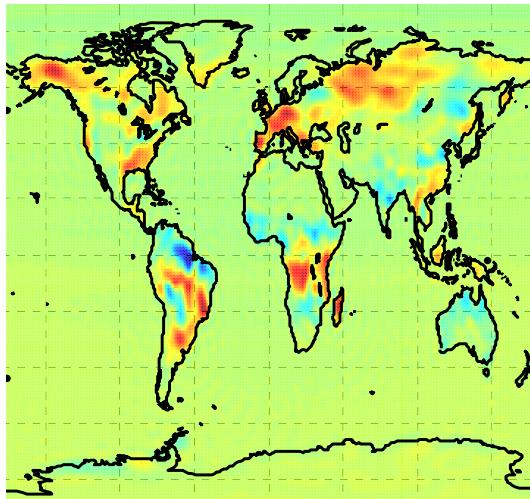
Repeat Period (revs/sidereal days)	Altitude (km)	Indination (deg)
363/23	317	90
238/15	293	90
159/10	283	90

GFO with multiple satellite pairs

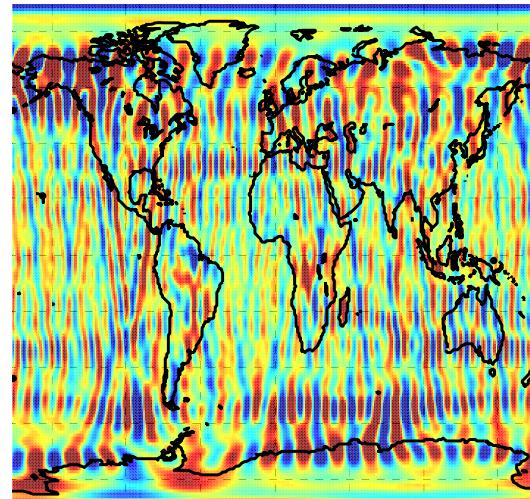
- Simulation setup
 - Satellites have laser interferometer and fly drag-free
 - AOD and tidal errors are included
 - Length of simulations: 10, 15, and 23 days
 - Spherical harmonics solved to degree and order 60
 - Low degree and order gravity fields can be estimated daily to correct the final multi-day solution (reduces the effect of temporal aliasing errors)

Results: plots in cm of water

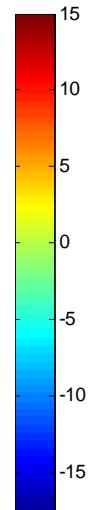
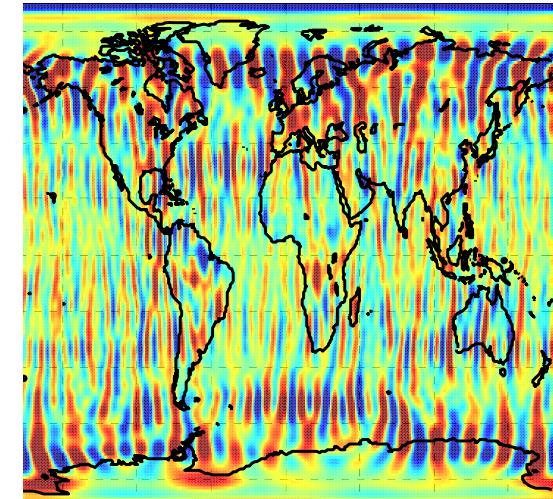
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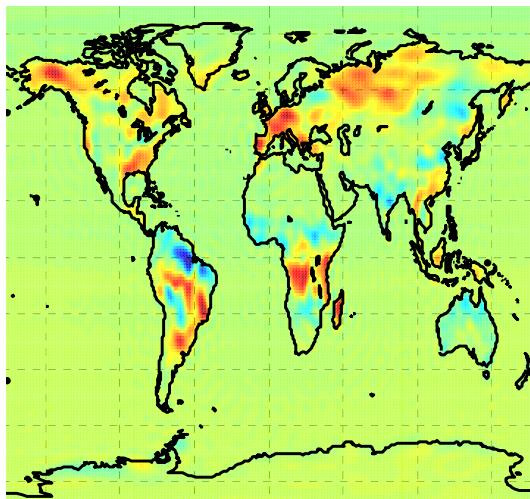
Single polar pair (15 day)



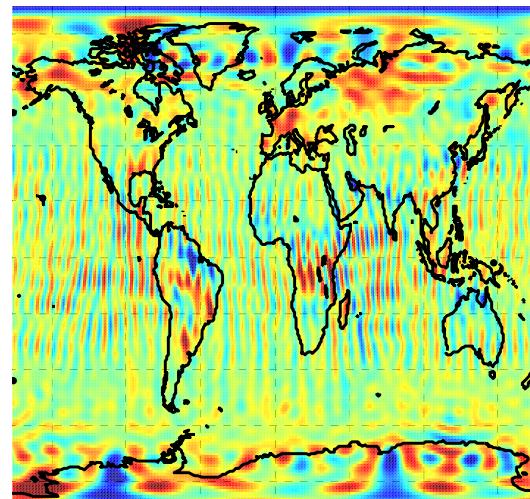
Single polar pair (15 day),
estimate daily 10x10 fields



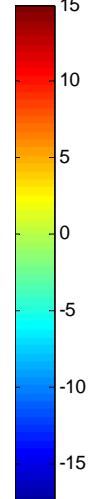
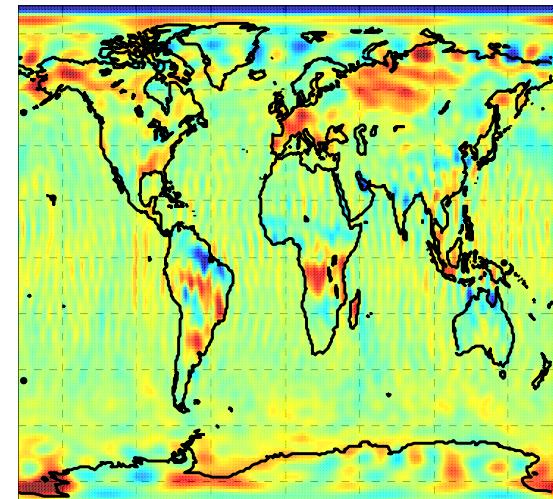
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Multiple pairs (15 + 5 day)



Multiple pairs (15 + 5 day),
estimate daily 20x20 field



GFO with multiple satellite pairs

- Comparison of performance for different configurations

Mission configuration		Hydrology error RMS (cm of water)	Ice mass error RMS (cm of water)
<u>Single Polar Pair</u> (estimating daily 10x10 fields)	10 day	11.3	8.3
	15 day	8.2	7.0
	23 day	7.6	6.2
<u>Multiple Pairs</u> (estimating daily 20x20 fields)	10 day + 5 day	2.6	5.2
	15 day + 5 day	1.9	4.9
	23 day + 5 day	2.2	6.3

Future work

- Increase fidelity of simulations to higher degree and order
- Further examine post-processing techniques such as Gaussian smoothing and de-striping
- Design more configurations and perform trade studies (different repeat periods, inclinations, formation types)
- Possible application of a global mascon estimation technique to achieve optimal solution with use of spatial constraints

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